

Advanced Topics in Geometry E (MTH.B501)

Linear Ordinary Differential Equations

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Ordinary Differential Equations

常微分方程

④ **solution**

unknown vector valued.

$\frac{d}{dt} \underline{x}(t) = f(t, \underline{x}(t)),$ $f: I \times U \rightarrow \mathbb{R}^m$

$\underline{x}(t_0) = \underline{x}_0$ initial condition

of (parameter) $I \subset \mathbb{R}, U \subset \mathbb{R}^m$

① ► Existence

② ► Uniqueness

③ ► Regularity on initial conditions and parameters

① $\exists \underline{x}: (t_0 - \varepsilon, t_0 + \varepsilon) \rightarrow \mathbb{R}^m$ C^1 local sol.

② maximal sol. $\underline{x}: J \subset I \rightarrow \mathbb{R}^m$ is unique

③ $\underline{x} = \underline{x}(t_0, \underline{x}_0, \underline{\alpha})(t) : C^\infty$

the initial value problem of ordinary differential equation.

Example

(m=1)

$$\textcircled{1} \quad \frac{d}{dt}x(t) = f(t, x(t)) = \lambda x(t) \quad x(0) = x_0.$$

linear in x λ : const.
 $t_0 = 0$

$x(t) = x_0 \cdot \exp(\lambda t)$ is the solution of $\textcircled{1}$
unique

on \mathbb{R}

Example

$$\mathbf{x} = \begin{pmatrix} x \\ y \end{pmatrix} \quad m=2$$

$m \in \mathbb{R}$

$$\Rightarrow \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} x_0 \cos \omega t + \frac{y_0}{\omega} \sin \omega t \\ -x_0 \omega \sin \omega t + y_0 \cos \omega t \end{pmatrix}$$

lineair in (x, y)

* $\begin{cases} \frac{dx}{dt} = y \\ \frac{dy}{dt} = -\omega^2 x \end{cases}$

$x(0) = x_0$

$y(0) = y_0$

$= \begin{pmatrix} y \\ -\omega^2 x \end{pmatrix}$

$$\begin{pmatrix} 0 & 1 \\ -\omega^2 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \left(\frac{d^2 x}{dt^2} = -\omega^2 x \right)$$

Example the logistic of.

t-1

f

$$\frac{dx}{dt} = \lambda x(a-x)$$

$$\frac{dx}{dt} = 1 + x^2,$$

$$x(0) = 0.$$

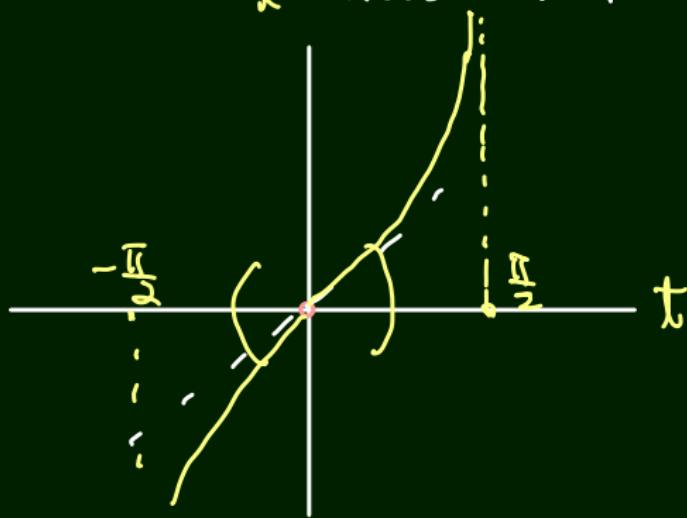
$$\frac{dx}{dt} = f(t, x) = 1 + x^2$$

$f: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$

UH

$$x(t) = \tan t \quad i$$

$$t \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$$



$$\begin{cases} \frac{dx}{dt} = e^t(1+x^2) \\ x = \tan e^t \end{cases}$$