

Advanced Topics in Geometry E (MTH.B501)

Integrability Conditions

可積分条件

Kotaro Yamada

kotaro@math.titech.ac.jp

<http://www.math.titech.ac.jp/~kotaro/class/2022/geom-e/>

Tokyo Institute of Technology

2022/04/26

Key

$$f_{xy} = f_{yx}$$

compatibility cond.
適合条件

Integrability Conditions

over-determined partial differential eq

$\text{m} \times \text{n}$, matrix-valued

$$\frac{\partial X}{\partial u^j} = X \Omega_j \quad (j = 1, \dots, m), \quad \underline{X(P_0) \neq X_0.} \quad (*)$$

($m \times n^2$ -equality)

on $U \subset \mathbb{R}^m$

initial condition

Proposition (Prop. 2.3)

for n^2 -unknowns (domain)

If a matrix-valued C^∞ function $X: U \rightarrow \text{GL}(n, \mathbb{R})$ satisfies (*), it holds that

\oplus

$$\boxed{\frac{\partial \Omega_j}{\partial u^k} - \frac{\partial \Omega_k}{\partial u^j} = \Omega_j \Omega_k - \Omega_k \Omega_j}$$

solution

regular matrices

for each (j, k) with $1 \leq j < k \leq m$.

(compatibility)

integrability condition

Our goal : $U : \boxed{\text{simply connected}}$, \oplus

Theorem 2.5 $\Rightarrow \exists^1 X: U \rightarrow M_n(\mathbb{R})$ satisfying (*)

$$\frac{\partial X}{\partial u^j} = X \Omega_j \quad (j = 1, \dots, m)$$

$$X \frac{\partial}{\partial u^k} \frac{\partial X}{\partial u^i} = \frac{\partial X}{\partial u^k} \Omega_j + X \frac{\partial \Omega_j}{\partial u^k}$$

$$\parallel = \cancel{X} \left(\Omega_k \Omega_j + \frac{\partial \Omega_i}{\partial u^k} \right)$$

$$X \frac{\partial}{\partial u^i} \frac{\partial X}{\partial u^k} = \cancel{X} \left(\Omega_j \Omega_k + \frac{\partial \Omega_k}{\partial u^i} \right)$$

Integrability Conditions

Lemma (Lem. 2.4)

Let $\Omega_j : U \rightarrow M_n(\mathbb{R})$ ($j = 1, \dots, m$) be C^∞ -maps defined on a domain $U \subset \mathbb{R}^m$ which satisfy

$$\frac{\partial \Omega_j}{\partial u^k} - \frac{\partial \Omega_k}{\partial u^j} = \Omega_j \Omega_k - \Omega_k \Omega_j.$$

Then for each smooth map

$$\sigma : D \ni (t, w) \longmapsto \sigma(t, w) = (u^1(t, w), \dots, u^m(t, w)) \in U$$

defined on a domain $D \subset \mathbb{R}^2$, it holds that

$$\frac{\partial T}{\partial w} - \frac{\partial W}{\partial t} - TW + WT = 0,$$

where $T := \sum_{j=1}^m \tilde{\Omega}_j \frac{\partial u^j}{\partial t}$, $W := \sum_{j=1}^m \tilde{\Omega}_j \frac{\partial u^j}{\partial w}$, ($\tilde{\Omega}_j := \Omega_j \circ \sigma$).

Integrability Conditions

$$\frac{\partial X}{\partial u^j} = X \Omega_j \quad (j = 1, \dots, m), \quad X(P_0) = X_0. \quad (*)$$

Lemma (Lem. 2.1)

Let $X: U \rightarrow M_n(\mathbb{R})$ be a C^∞ -map satisfying (*). Then for each smooth path $\gamma: I \rightarrow U$ defined on an interval $I \subset \mathbb{R}$,
 $\hat{X} := X \circ \gamma : I \rightarrow M_n(\mathbb{R})$ satisfies the ordinary differential equation

$$\frac{d\hat{X}}{dt}(t) = \hat{X}(t) \Omega_\gamma(t) \quad \left(\Omega_\gamma(t) := \sum_{j=1}^n \Omega_j \circ \gamma(t) \frac{du^j}{dt}(t) \right)$$

on I , where $\gamma(t) = (u^1(t), \dots, u^m(t))$.

Integrability of Linear systems $P_0 \in \mathbb{U} \subset (\mathbb{R}^m; (u^1, \dots, u^m))$

$$\Omega_j : \mathbb{U} \rightarrow M_n(\mathbb{R}) \quad C^\infty$$

↑ a domain (arcwise connected open)

$$\underbrace{\frac{\partial X}{\partial u^j} = X \Omega_j}_{(j = 1, \dots, m)}, \quad X(P_0) = X_0. \quad (1)$$

$$\underbrace{\frac{\partial \Omega_j}{\partial u^k} - \frac{\partial \Omega_k}{\partial u^j} = \Omega_j \Omega_k - \Omega_k \Omega_j}_{(2)}$$

Theorem (Thm. 2.5)

Let $\Omega_j : U \rightarrow M_n(\mathbb{R})$ ($j = 1, \dots, m$) be C^∞ -functions defined on a simply connected domain $U \subset \mathbb{R}^m$ satisfying (2). Then for each $P_0 \in U$ and $X_0 \in M_n(\mathbb{R})$, there exists the unique $n \times n$ -matrix valued function $X : U \rightarrow M_n(\mathbb{R})$ satisfying (1).



All loops are contractible

$\bar{\Omega}^n$ (i.e. homotopy equivalent to a point)

Proof of Thm 2.5 (outline)

- Determine $X(Q)$ for $Q \in U$

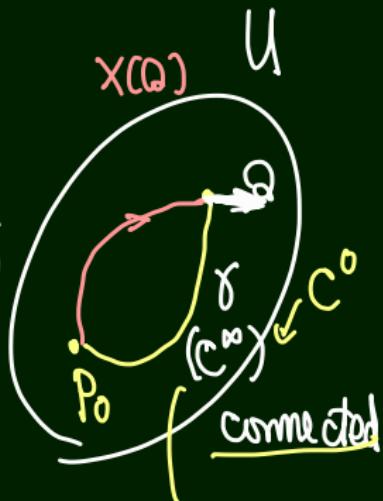
① Solve linear ODE along a path γ
joining P_0 to Q

X_γ : the terminal value

② Show that X_γ does not depend on γ .

- simple connectedness
- compatibility.

③ Show $Q \mapsto X(Q)$: the desired solution.



Whitney's
approximation

Exercise
Compute
 $(\frac{\partial X}{\partial t})$

$$\textcircled{1} \quad Y(t) = (u^1(t) \cdots u^m(t)) ; \quad C^{\infty}$$

$$Y(0) = P_0, \quad f(1) = Q$$

- If X satisfies $\frac{\partial X}{\partial u^j} = X \Omega_j$

then $\hat{X} = X \circ f = X(u^1(t) \cdots u^m(t))$ P_0 satisfies

Lemma
2.1 $\frac{d\hat{X}}{dt} = \hat{X} \Omega_f$ $\stackrel{\text{linear}}{\sim}$ $\Omega_f := \sum_{j=1}^m \Omega_j \circ \frac{du^j}{dt}$

" chain rule

$\leq \int \frac{\partial X}{\partial u^j} \frac{du^j}{dt} dt$

Solve $\textcircled{*}$ with initial cond
 $\hat{X}(0) = X_0$,
and set $X_f := \hat{X}(1)$

② Claim $X_{f_1} = X_{f_2}$ Whitney U

- $\sigma: [0, 1] \times [0, 1] \rightarrow U (C^\infty)$

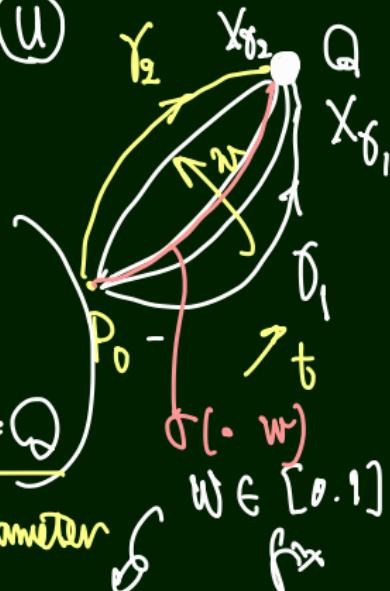
$$\begin{cases} \sigma(t, 0) = f_1(t) \\ \sigma(t, 1) = f_2(t) \end{cases}$$

$$\sigma(0, w) = P_0 \quad \sigma(1, w) = Q$$

C^0 homotopy joining f_1 & f_2 parameter w fix

- $\tilde{X}(t, w) :$ $\left\{ \begin{array}{l} \frac{d\tilde{X}}{dt}(\cdot, w) = \tilde{X}\Omega \\ \tilde{X}(0, w) = X_0 \end{array} \right.$

$$\tilde{X}: [0, 1] \times [0, 1] \rightarrow M_n(\mathbb{R}) \quad C^\infty$$



Claim $\tilde{X}(1, w)$ is constant in w .

$$(T) := \Omega_{\sigma(\cdot, w)} = \sum_{j=1}^m \Omega_j \frac{\partial u^j}{\partial t} \quad \sigma(1, w) = (u^1, \dots, u^m)$$

$$W := \sum_{j=1}^m \Omega_j \frac{\partial u^j}{\partial w}$$

$$\boxed{\frac{\partial \tilde{X}}{\partial t} = \tilde{X} T}$$

We shall prove $\frac{\partial \tilde{X}}{\partial w} = \tilde{X} W$ compatibility

\Rightarrow the claim follows $(\because W(1, w) = 0)$



$$\sigma(1, w) = Q$$

$$\underline{\text{Lemma}} \quad T_w - W_t = TW - WT \quad \stackrel{\text{Lem}}{=} \quad (2.4)$$

compatibility condition

$$(\tilde{X}_w)_t = \tilde{X}_{tw} = (\tilde{X}T)_w = \tilde{X}_w T + \cancel{\tilde{X}T_w}$$

$$= \tilde{X}_w T + \tilde{X}(W_t + TW - WT)$$

$$= \cancel{\tilde{X}_w T} + \underline{(\tilde{X}W)_t} - \cancel{\frac{\tilde{X}_w W}{T}} + \cancel{\tilde{X}IW} - \cancel{\tilde{X}WT}$$

$$\frac{(\tilde{X}_w - \tilde{X}W)_t}{Y} = \frac{(\tilde{X}_w - \tilde{X}W)T}{Y}$$

$$Y_t = YT \quad Y(0, w) = 0$$

$$Y = \tilde{X}_w - \tilde{X}W = 0. \quad \square$$

Application: Poincaré's lemma

Theorem (Poincaré's lemma)

If a differential 1-form

$$\omega = \sum_{j=1}^m \alpha_j(u^1, \dots, u^m) du^j$$

defined on a simply connected domain $U \subset \mathbb{R}^m$ is closed, that is, $d\omega = 0$ holds, then there exists a C^∞ -function f on U such that $df = \omega$. Such a function f is unique up to additive constants.

Application: Conjugation of harmonic functions

Theorem

Let $U \subset \mathbb{C} = \mathbb{R}^2$ be a simply connected domain and $\xi(u, v)$ a C^∞ -function harmonic on U . Then there exists a C^∞ harmonic function η on U such that $\xi(u, v) + i\eta(u, v)$ is holomorphic on U .

⊕: Cauchy-Riemann

$$\begin{array}{c} \text{Cauchy} \\ \Rightarrow \end{array} \left\{ \begin{array}{l} \xi_{uu} + \overline{\xi}_{vv} = 0 \\ \eta_u = -\xi_v \\ \eta_v = \xi_u \end{array} \right. \quad \leftrightarrow \quad \left\{ \begin{array}{l} \varphi = e^\eta \\ \varphi_u = -\xi_v \varphi \\ \varphi_v = \xi_u \varphi \end{array} \right. \quad \text{Riemann}$$

(compatibility
 $\Delta \xi = 0$)
⊗

Application: Conjugation of harmonic functions

Example

$$\xi(u, v) = e^u \cos v$$

$$\underline{\Delta \xi = 0}$$

in \mathbb{D}

$$\Rightarrow \eta = \underline{e^u \sin v}$$

$$\begin{aligned}\xi + i\eta &= e^u (\cos v + i \sin v) \\ &= e^{u+iw}\end{aligned}$$

Exercise 2-1

Problem

Let $\xi(u, v) := \log \sqrt{u^2 + v^2}$ be a function defined on
 $U := \mathbb{R}^2 \setminus \{(0, 0)\}$

1. Show that ξ is harmonic on U .
2. Find the conjugate harmonic function η of ξ on

$$V = \mathbb{R}^2 \setminus \{(u, 0) \mid u \leq 0\} \subset U.$$

3. Show that there exists no conjugate harmonic function of ξ defined on U .



Exercise 2-2

Problem

Let $\theta = \theta(u, v)$ be a smooth function on a domain $U \subset \mathbb{R}^2$ such that $0 < \theta < \pi$, and set

$$\Omega := \begin{pmatrix} \theta_u \cot \theta & 0 & \cot \theta \\ -\theta_u \csc \theta & 0 & -\csc \theta \\ 0 & \sin \theta & 0 \end{pmatrix}, \quad \Lambda := \begin{pmatrix} 0 & -\theta_v \csc \theta & -\csc \theta \\ 0 & \theta_v \cot \theta & \cot \theta \\ \sin \theta & 0 & 0 \end{pmatrix}.$$

Prove that the compatibility condition of a system of partial differential equation

$$\underbrace{\frac{\partial \mathcal{F}}{\partial u}}_{=} = \mathcal{F}\Omega, \quad \underbrace{\frac{\partial \mathcal{F}}{\partial v}}_{=} = \mathcal{F}\Lambda$$

is equivalent to

$$\theta_{uv} = \sin \theta.$$

Exercise 2-3

Problem

Let $\mathbf{v} = \mathbf{v}(x, y, z)$ be a vector field defined on a simply connected domain U in $(\mathbb{R}^3; (x, y, z))$. Assume that \mathbf{v} is irrotational, that is, $\text{rot } \mathbf{v} = \mathbf{0}$. Then there exists a function $\varphi: U \rightarrow \mathbb{R}$ such that $\mathbf{v} = \text{grad } \varphi$.