

Advanced Topics in Geometry F (MTH.B502)

Riemannian connection

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Exercise 1-1

Problem

Let $U \subset \mathbb{R}^n$ be a domain and g a Riemannian metric on U . Show that

1. There exists an n -tuple of vector fields $\{e_1, \dots, e_n\}$ such that

$$g(e_i, e_j) = \delta_{ij} = \begin{cases} 1 & (i = j) \\ 0 & (\text{otherwise}) \end{cases}.$$

2. Take another n -tuple $\{v_1, \dots, v_n\}$ satisfying $g(v_i, v_j) = \delta_{ij}$. Then there exists a matrix-valued function

$$\Theta: U \rightarrow O(n) \quad [e_1, \dots, e_n] = [v_1, \dots, v_n]\Theta.$$

Exercise 1-2

Problem

Let $\mathbb{R}_1^{n+1} = (\mathbb{R}^{n+1}, \langle \cdot, \cdot \rangle_L)$ be the Minkowski vector space. Show that if $v \in \mathbb{R}_1^{n+1}$ satisfies $\langle v, v \rangle_L = -1$, the orthogonal complement

$$v^\perp := \{x \in \mathbb{R}_1^{n+1}; \langle v, x \rangle_L = 0\}$$

is an n -dimensional space-like subspace of \mathbb{R}_1^{n+1} .

Lie Bracket

$X, Y \in \mathfrak{X}(M)$:

$$[X, Y]: \mathcal{F}(M) \ni f \longmapsto X(Yf) - Y(Xf) \in \mathcal{F}(M).$$

- ▶ bilinear, skew-symmetric
- ▶ $[fX, Y] = f[X, Y] - (Yf)X$
- ▶ $[X, fY] = f[X, Y] + (Xf)Y$
- ▶ $[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = \mathbf{0},$

Lie Bracket as integrability

Fact (Fact 2.1)

Let (X_1, \dots, X_n) be an n -tuple of vector fields on n -dimensional manifolds, which is linearly independent in $T_p M$ for each $p \in M$. Then existence of local coordinate system (x^1, \dots, x^n) around p such that $\partial/\partial x^j = X_j$ ($j = 1, \dots, n$) is equivalent to that $[X_j, X_k] = \mathbf{0}$ holds for all $j, k = 1, \dots, n$.

Tensors

Lemma (Lemma 2.2)

A linear map $\omega: \mathfrak{X}(M) \rightarrow \mathcal{F}(M)$ is a 1-form if and only if

$$\omega(fX) = f\omega(X) \quad (f \in \mathcal{F}(M), X \in \mathfrak{X}(M)).$$

Lemma (Lemma 2.3)

A bilinear map $\alpha: \mathfrak{X}(M) \times \mathfrak{X}(M) \rightarrow \mathcal{F}(M)$ is a $(0, 2)$ -tensor if and only if

$$\alpha(fX, Y) = \alpha(X, fY) = f\alpha(X, Y) \quad (f \in \mathcal{F}(M), X, Y \in \mathfrak{X}(M))$$

holds.

Differential Forms

- ▶ $\wedge^0(M) := \mathcal{F}(M),$
- ▶ $\wedge^1(M) := \Gamma(T^*M),$
- ▶ $\wedge^2(M) := \{\omega \in \Gamma(T^*M \otimes T^*M); \text{skew-symmetric}\}$

Exterior product

Exterior derivative

- ▶ $f \in \wedge^0(M) \Rightarrow df(X) = Xf.$
- ▶ $\alpha \in \wedge^1(M) \Rightarrow d\alpha(X, Y) = X\alpha(Y) - Y\alpha(X) - \alpha([X, Y])$