

Advanced Topics in Geometry F (MTH.B502)

Fundamental Theorem for surfaces

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Surfaces in 3-manifolds

(N^3, g) : a Riemannian 3-manifold.

- ▶ $f: M^2 \rightarrow N^3$: an immersion.
- ▶ $ds^2(X, Y) := g(df(X), df(Y))$: the first fundamental form
- ▶ $[e_1, e_2]$: an orthonormal frame on $(U \subset M^2, ds^2)$
- ▶ $[v_1, v_2] := [df(e_1), df(e_2)]$
- ▶ v_3 : the unit normal vector field

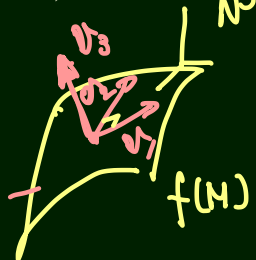
(M^2, ds^2) : Riemannian mfd

linear.
 $\mathbb{R}: T_p M \rightarrow T_p M$

$$h^j := -g(dv_3, v_j) \quad (j = 1, 2)$$

$$h := h^1 e_1 + h^2 e_2$$

the second f. f.
the shape operator



The second fundamental forms

normal

$$h^j := -g(d\nu_B, \underline{v_j}) \quad (j = 1, 2) \quad \text{1 form}$$
$$\{h_i^j\} = h^j(e_i)$$
$$h := h^1 e_1 + h^2 e_2$$
$$\begin{pmatrix} h_1^1 & h_2^1 \\ h_1^2 & h_2^2 \end{pmatrix} = \begin{pmatrix} h_1^1 & h_2^1 \\ h_1^2 & h_2^2 \end{pmatrix}$$

Lemma (Lem. 7.1)

$$h_2^1 = h_1^2.$$

$$df = \omega^1 \nu_1 + \omega^2 \nu_2$$
$$0 = ddf = \dots \nu_1 + \dots \nu_2 -$$
$$\underline{\underline{(\omega^1 \wedge h^1 + \omega^2 \wedge h^2) \nu_3}}$$

$$\omega^1 \wedge h^1 + \omega^2 \wedge h^2 = 0$$

$$\Leftrightarrow (\omega^1 \wedge h^1)(\theta_1, \theta_2) + (\omega^2 \wedge h^2)(\theta_1, \theta_2) = 0$$

$$\underbrace{\omega^1(\theta_1) h^1(\theta_2)} + \underbrace{\omega^2(\theta_2) h^2(\theta_1)} - \underbrace{\omega^1(\theta_2) h^1(\theta_1)} - \underbrace{\omega^2(\theta_1) h^2(\theta_2)} = 0$$

$$\Leftrightarrow h^1_{\theta_2} - h^2_{\theta_1} = 0$$

$$\omega^i(\theta_j) = \delta^i_j$$

The second fundamental forms

$$h^j := -g(dv_3, v_j) \quad (j = 1, 2)$$

$$h_i^j = h^j(e_i)$$

$$h_i := h^1 e_1 + h^2 e_2$$

$$\begin{pmatrix} h_1^1 & h_1^2 \\ h_2^1 & h_2^2 \end{pmatrix}$$

Definition (Def. 7.2)

det

外曲率

exterior curvature

$$K_{\text{ext}} := h_1^1 h_2^2 - h_2^1 h_1^2 = h^1 \wedge h^2(e_1, e_2),$$

$$H = \frac{h_{11} + h_{22}}{2}$$

the mean curvature

$$\begin{pmatrix} h_1^1 \\ h_2^2 \end{pmatrix}$$

The Fundamental Theorem

$$N^3 = N^3(k_0) := \begin{cases} H^3(k_0) \\ \mathbb{R}^3 \\ S^3(k_0) \end{cases} \begin{array}{l} \text{the hyperbolic sp} \\ (k_0 < 0), \cdot SO(3,1) \\ (k_0 = 0), \cdot SO(3) \times \mathbb{R}^3 \\ (k_0 > 0), \cdot SO(4) \end{array}$$

\swarrow \mathbb{R}^3 \searrow
 the sphere

(simply connected) space forms

(N^3, g) : Riem. mfd. connected (complete Riem. mfd
compact of int) of const
sec curv
 $G := \text{Isom}_0(N^3, g) := \text{the isometry group}$
 " a Lie group $\dim G \leq 6$ " = " $\Leftrightarrow N^3 = N^3(k_0)$

Surfaces in space Forms

曲面論の基本定理.

Theorem (The fundamental theorem for surfaces, Thm. 7.4)

- ▶ $U \subset \mathbb{R}^2$: a simply connected domain
- ▶ ds^2 : a Riemannian metric on U . (1st f.f.)
- ▶ $[e_1, e_2]$: an orthonormal frame; $\mu = \omega_2^1$: the connection form.
- ▶ k : the sectional curvature.
- ▶ h^1, h^2 : one forms on U ; $K_{\text{ext}} = h^1 \wedge h^2(e_1, e_2)$ ext. curvature.

Assume

- 2nd f.f.
- 1. $k = K_{\text{ext}} + k_0$
 - 2. $dh^1 = h^2 \wedge \mu, dh^2 = -h^1 \wedge \mu$

Integrability

$\Rightarrow \exists f: U \rightarrow N^3(k_0)$ with ds^2 and $h = h^1 e_1 + h^2 e_2$ as the fundamental forms.

Surfaces in space Forms

- ▶ $f: U \rightarrow N^3(k_0)$: an immersion
- ▶ $[e_1, e_2]$: an orthonormal frame; $\underline{\mu} = \omega_2^1$: the connection form.
- ▶ $h = h^1 e_1 + h^2 e_2$: the second fundamental form.
- ▶ $\mathcal{F} = (\underline{v}_1, \underline{v}_2, \underline{v}_3)$: an adapted frame.

$$k_0 = 0$$

\mathbb{R}^3

$$v_j = df(e_j)$$

$$v_3 = v_1 \times v_2$$

$$d\mathcal{F} = \mathcal{F}\tilde{\Omega}, \quad \tilde{\Omega} = \begin{pmatrix} 0 & \mu & -h^1 \\ -\mu & 0 & -h^2 \\ h^1 & h^2 & 0 \end{pmatrix}$$

$$d\omega_2^1$$

$$d\mu = k \omega^1 \wedge \omega^2$$

integrability: $d\tilde{\Omega} + \tilde{\Omega} \wedge \tilde{\Omega} = 0$

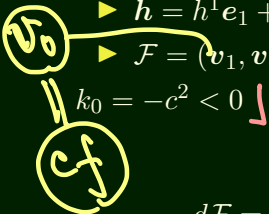
$$\rightarrow d\mu - k \omega^1 \wedge \omega^2 = 0 \quad \text{Kont. } \omega^1 \wedge \omega^2 \quad \text{Goursat}$$

$$dR^1 = h^2 \wedge \mu, \quad dR^2 = -h^1 \wedge \mu$$

Codazzi

Surfaces in space Forms

- ▶ $f: U \rightarrow N^3(k_0)$: an immersion
- ▶ $[e_1, e_2]$: an orthonormal frame; $\mu = \omega_2^1$: the connection form.
- ▶ $h = h^1 e_1 + h^2 e_2$: the second fundamental form
- ▶ $\mathcal{F} = (v_1, v_2, v_3)$: an adapted frame.



$$d\mathcal{F} = \mathcal{F}\tilde{\Omega}, \quad \tilde{\Omega} = \begin{pmatrix} 0 & c\omega^1 & c\omega^2 & 0 \\ c\omega^1 & 0 & \mu & -h^1 \\ c\omega^2 & -\mu & 0 & -h^2 \\ 0 & h^1 & h^2 & 0 \end{pmatrix}.$$

$$\tilde{R} = K_{ext} + k_0$$

Integrability

$$d\mu + \underbrace{c^2 \omega^1 \wedge \omega^2} - \underbrace{h^1 \wedge h^2} = 0$$

Same as the case $k_0 = 0 \rightarrow dh^1 = h^2 \wedge \mu, \quad dh^2 = -h^1 \wedge \mu$

Application

Lawson Correspondence. $H = \frac{1}{2}(h^1 + h^2)$

Theorem (Thm. 7.6)

Let $f: U \rightarrow N^3(k_0)$ be an immersion of constant mean curvature H defined on a simply-connected domain $U \subset \mathbb{R}^2$. Then there exists an immersion $f_{\tilde{k}_0}: U \rightarrow N^3(\tilde{k}_0)$ of constant mean curvature $H + t$ sharing the first fundamental form with f , where $\tilde{k}_0 = \cancel{H} - t^2 - 2Ht$.

$$\hat{h}^1 := h^1 + t\omega^1 \quad \hat{h}^2 := h^2 + t\omega^2$$

$$\begin{aligned} d\hat{h}^1 &= \underline{dh^1} + t d\omega^1 = h^2 \wedge \mu + t \omega^2 \wedge \mu \\ &= (h^2 + t\omega^2) \wedge \mu = \hat{h}^2 \wedge \mu \quad \text{etc} \end{aligned}$$

(\hat{h}^1, \hat{h}^2) satisfies the codazzi eq.

$$\begin{aligned}
 \tilde{h}^1 \wedge \tilde{h}^2 &= (h^1 + t\omega^1) \wedge (h^2 + t\omega^2) \\
 &= h^1 \wedge h^2 + t(h^1 \wedge \omega^2 + \omega^1 \wedge h^2) \\
 &\quad + t^2 \omega^1 \wedge \omega^2
 \end{aligned}$$

(0, 0)

$$\hat{K}_{ext} = K_{ext} + 2tH + t^2$$

$$\cancel{K} - \hat{k}_0 = \cancel{K} - k_0 + 2tH + t^2$$

Setting $\hat{k}_0 = k_0 - 2tH - t^2$

$(ds^2, \tilde{h}^1, \tilde{h}^2)$ satisfies the integrability
in $N^3(\tilde{k}_0)$

Example

Example

$$R_0 = 0$$

$$H = 0$$

$$t = 1$$

Let $f: U \rightarrow \mathbb{R}^3$ be a minimal surface (that is, with zero mean curvature). Then there exists $f_1: U \rightarrow H^3(-1)$ of constant mean curvature 1 with the same first fundamental form as f .

$$H = 0 \text{ in } \mathbb{R}^3$$

Weierstrass repr.

← complex analytic data

$$H = 1 \text{ in } H^3(-1) f.$$

Bryant's formula

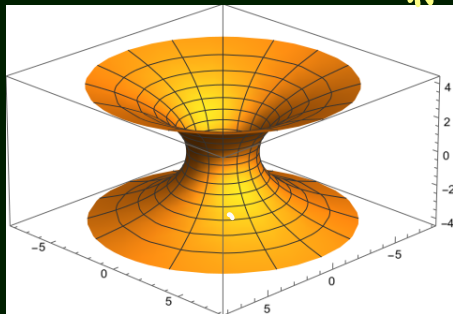
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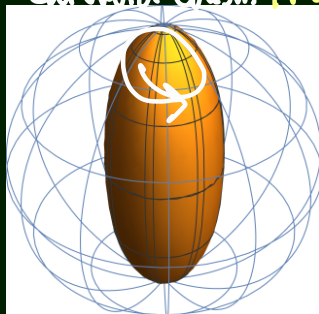
Example

catenoid

\mathbb{R}^3

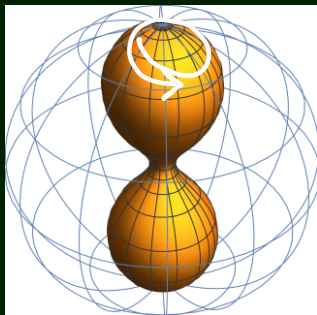
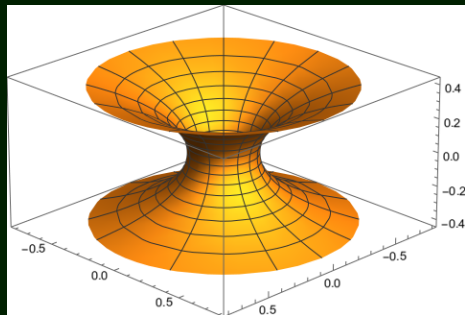


catenoid cousin $H^3(-1)$

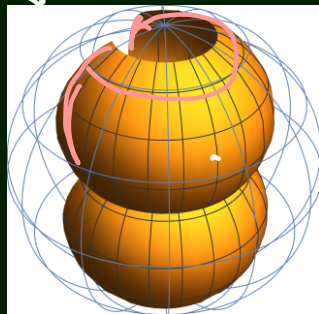
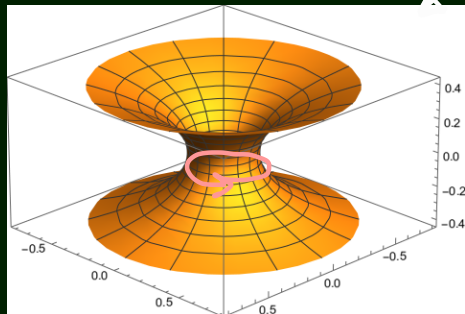


Poincaré
model

Example



Example



Lawson correspondence : local correspondence.

- ▶ R. Osserman, A survey of minimal surfaces, Van Nostrand, 1969; Dover 1986/2002
- ▶ R. Bryant, Astérisque, 1987
- ▶ M. Umehara and K. Y., Ann. Math. 1993, Crelle 1995...