

Advanced Topics in Geometry E1 (MTH.B505)

Pseudo Riemannian manifolds

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Exercise 2-1

Parametrization of the hyperbolic plane

Problem (Ex. 2-1)

(can be generalized to

higher dim
case)

Let $D := \{(u, v) \in \mathbb{R}^2; u^2 + v^2 < 1\}$, and set

$$f : D \ni (u, v) \mapsto \frac{1}{1 - u^2 - v^2} (1 + u^2 + v^2, 2u, 2v) \in \mathbb{L}^3.$$

For each $(u, v) \in D$,

- ▶ Show that f is a bijection from D to $H^3(-1)$.
- ▶ Compute $\langle f_u, f_u \rangle$, $\langle f_u, f_v \rangle$ and $\langle f_v, f_v \rangle$.
- ▶ For each $(u, v) \in D$, find an orthonormal basis $[e_1(u, v), e_2(u, v)]$ of $T_x H^3(-1)$, where $x = f(u, v)$.

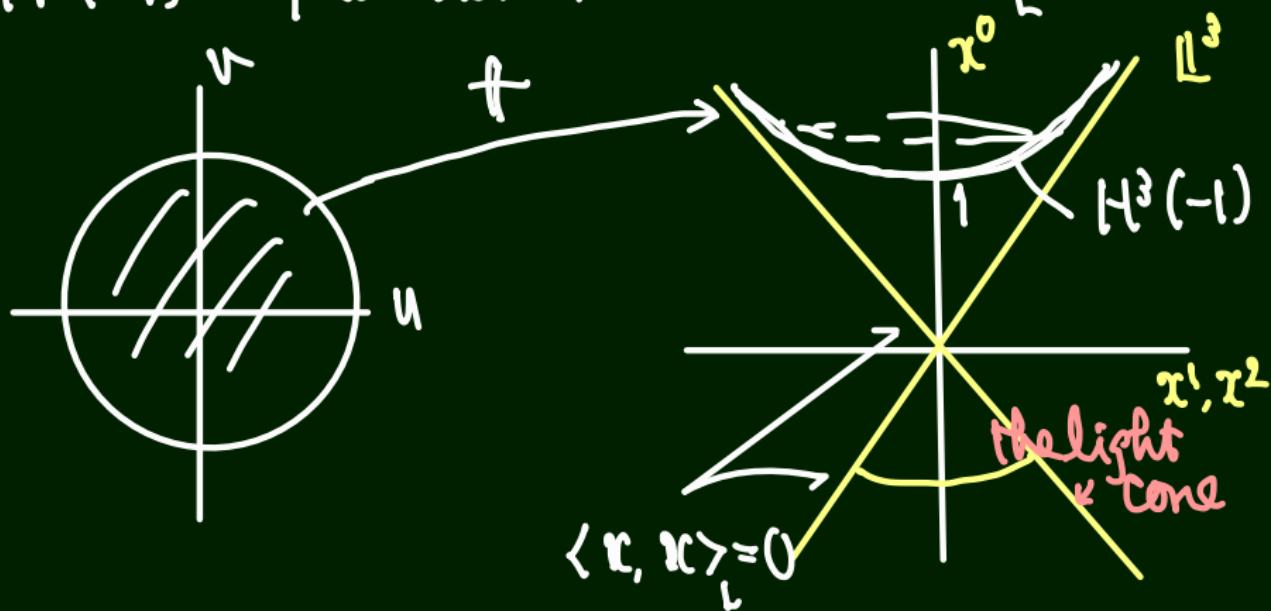
Exercise 2-1

$$D = \{(u, v) \mid u^2 + v^2 < 1\} \subset \mathbb{R}^2$$

$$\mathbb{L}^3 = (\mathbb{R}^3, \langle \cdot, \cdot \rangle) \quad -(\mathbf{x}^0)^2 - (\mathbf{x}^1)^2 - (\mathbf{x}^2)^2 = 1$$

$$f : D \ni (u, v) \mapsto \frac{1}{1 - u^2 - v^2} (1 + u^2 + v^2, 2u, 2v) \in \mathbb{L}^3. \quad = -1$$

$$H^3(-1) = \left\{ \mathbf{x} = (x^0, x^1, x^2) \in \mathbb{L}^3 ; \langle \mathbf{x}, \mathbf{x} \rangle_{\mathbb{L}} = -1, \langle \mathbf{x}, \mathbf{0} \rangle_{\mathbb{L}} = 0 \right\}$$



Exercise 2-1

analogue of the stereographic proj
 $H^3(-1)$

$$f : D \ni (u, v) \mapsto \frac{1}{1 - u^2 - v^2} (1 + u^2 + v^2, 2u, 2v) \in \mathbb{P}.$$

$$= (\chi^0, \chi^1, \chi^2)$$

$$\because (\chi^0 > 0, -(\chi^0)^2 + (\chi^1)^2 + (\chi^2)^2 = 1)$$

f is a bijection (i.e. 1 to 1, onto)

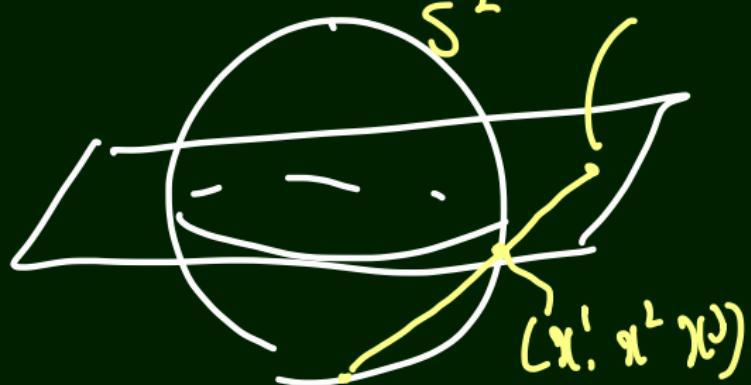
$$\begin{array}{ccc} H^3(-1) & \xrightarrow{\quad \text{?} \quad} & \frac{1}{1 + \chi^0} (\chi^1, \chi^2) \in D \\ \text{inverse} & & \text{exercise} \end{array}$$

Exercise 2-1

Poincaré disc model

$$f : D \ni (u, v) \mapsto \frac{1}{1-u^2-v^2} (1+u^2+v^2, 2u, 2v) \in \mathbb{H}^3$$

Stereographic proj



$$\chi = \frac{1}{1+u^2+v^2} (2u, 2v, u^2+v^2-1)$$



Exercise 2-1

$$f : D \ni (u, v) \mapsto \frac{1}{1-u^2-v^2} (1+u^2+v^2, 2u, 2v) \in \mathbb{L}^3.$$

$$\begin{cases} f_u = \frac{2}{(1-u^2-v^2)^2} (2u, 1+u^2-v^2, 2uv) \\ f_v = \frac{2}{(1-u^2-v^2)^2} (2v, 2uv, 1-u^2+v^2) \end{cases}$$

$$\langle f_u, f_u \rangle_L = \langle f_v, f_v \rangle_L = \frac{4}{(1-u^2-v^2)^2} > 0$$

$$\langle f_u, f_v \rangle_L = 0 \quad \frac{4}{(1-u^2-v^2)^2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} : \text{positive definite}$$

Exercise 2-1

$$f : D \ni (u, v) \mapsto \frac{1}{1-u^2-v^2} (1+u^2+v^2, 2u, 2v) \in \mathbb{L}^3.$$

For each (u, v) , $\underbrace{\text{Span}\{f_u, f_v\}}_{W} \subset T_x H^2(-1)$
 "positive definite" $\left(\langle \cdot, \cdot \rangle_L \Big|_{W \times W} \text{ is positive.} \right) \quad x = f(u, v)$

$$\checkmark e_1 = \frac{1-u^2-v^2}{2} f_u, \quad e_2 = \frac{1-u^2-v^2}{2} f_v \\ \Rightarrow [e_1, e_2] = 0$$

Exercise 2-2

Isometry $\nsubseteq S^n(k)$

Problem (Ex. 2-2)

Fix an $(n + 1) \times (n + 1)$ -orthogonal matrix A and set

$$\varphi: S^n(k) \ni \mathbf{x} \mapsto A\mathbf{x} \in \mathbb{R}^{n+1},$$

where k is a positive number. Fix $\mathbf{x} \in S^n(k)$ and take a smooth curve $\gamma(t)$ on $S^n(k)$ such that $\gamma(0) = \mathbf{x}$ and set
 $\mathbf{v} := \dot{\gamma}(0) \in T_{\mathbf{x}}S^n(k)$.

- ▶ Show that φ induces a bijection from $S^n(k)$ into $S^n(k)$.
- ▶ Show that $\varphi_*\mathbf{v} := \frac{d}{dt}\Big|_{t=0} \varphi \circ \gamma = A\mathbf{v}$.
- ▶ Verify that $\boxed{\langle \mathbf{v}, \mathbf{v} \rangle = \langle \varphi_*\mathbf{v}, \varphi_*\mathbf{v} \rangle}$

$$S^n(k) = \{ \mathbf{x} \in \mathbb{E}^{n+1}; \langle \mathbf{x}, \mathbf{x} \rangle = \frac{1}{k} \} (k > 0)$$

A: $(n+1) \times (n+1)$ orthogonal matrix

Recall A: orthogonal $AA^T = A^T A = I$

$$\Rightarrow \langle A\mathbf{x}, A\mathbf{y} \rangle = \langle \mathbf{x}, \mathbf{y} \rangle \quad \text{identity}$$

Euclidean inner product for $\mathbf{x}, \mathbf{y} \in \mathbb{E}^{n+1}$

$$\Rightarrow \varphi: S^n(k) \ni \mathbf{x} \mapsto \varphi(\mathbf{x}) = A\mathbf{x} \in S^n(k)$$

$$\varphi^{-1}(\mathbf{y}) = A^{-1}\mathbf{y} (= A^T \mathbf{y})$$

$\varphi: S^n(k) \rightarrow S^n(k)$: a bijection

* $x \in S^n(k)$, $v \in T_x S^n(k)$

$$v = \left. \frac{d}{dt} \right|_{t=0}^{\exists} \gamma(t) \quad \begin{array}{l} \cdot \gamma: \text{a curve in } S^n(k) \\ \cdot \gamma(0) = x \end{array}$$

* $\tilde{\gamma}(t) = \varphi(\gamma(t))$ $\tilde{\gamma}(0) = \varphi(x)$

$$\left. \frac{d}{dt} \right|_{t=0} \tilde{\gamma}(t) \stackrel{\approx}{=} \varphi_* v \quad \begin{array}{l} \tilde{\gamma}: \text{a curve in } S^n(k) \\ (\varphi_*: T_x N \rightarrow T_{\varphi(x)} M) \end{array}$$

$$\left. \frac{d}{dt} \right|_0 A \tilde{\gamma}(t) = A \dot{\tilde{\gamma}}(0) = \underline{A v}$$

$$\varphi_* v = Av$$

$$\Rightarrow \langle \varphi_* v, \varphi_* w \rangle = \langle Av, Aw \rangle$$

$$\underbrace{\qquad\qquad\qquad}_{\text{auf}} \simeq \overbrace{\qquad\qquad}^{\text{auf}}$$

φ is an isometry.

Definition

(bijection)

Let (M, g) be a Riemannian manifold. A smooth map $\varphi: M \rightarrow M$ is an isometry if

$$g(X, Y) = g(\varphi_* X, \varphi_* Y)$$

preserves
the inner product

holds for all tangent vectors X and Y of M .

Fact

Set of the isometries, called the isometry group, is a group with respect to composition of maps.

Fact

The isometry group of $S^n(k)$ contains the orthogonal group $O(n + 1)$.

$O(n+1) = \{ (n+1) \times (n+1) - \text{orthogonal matrix} \}$
the orthogonal group

Isometry group of $S^n(\mathbb{R}) \subset O(n+1)$

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Ex 2-2

Fact

$\text{Isom } S^n(\mathbb{R}) = O(n+1)$

(^{we} prove later)