

Advanced Topics in Geometry E1 (MTH.B505)

Hopf-Rinow's theorem

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Set up

(M, g) : a connected Riemannian manifold

Length

Definition

Let $\gamma: [a, b] \rightarrow M$ be a piecewise C^1 -curve, where $[a, b]$ is a closed interval on \mathbb{R} . The integral

$$\mathcal{L}(\gamma) := \int_a^b |\dot{\gamma}(t)| dt$$

is called the length of γ .

Distance

Lemma

For points $p, q \in M$, set

$$d(p, q) := \inf\{\mathcal{L}(\gamma) ; \gamma \in \mathcal{C}_{p,q}\} : M \times M \rightarrow \mathbb{R},$$

$$\left(\mathcal{C}_{p,q} := \left\{ \gamma : [a, b] \rightarrow M ; \begin{array}{l} \gamma \text{ is a piecewise } C^1\text{-curve} \\ \text{with } \gamma(a) = p \text{ and } \gamma(b) = q \end{array} \right\} \right)$$

is a distance function on M , that is, it satisfies the axiom

- $d(p, q) \geq 0$ for any $p, q \in M$. The equality holds iff $p = q$.
- $d(p, q) = d(q, p)$.
- $d(p, q) + d(q, r) \geq d(p, r)$

of distance (compatible to the topology of M).

d : the Riemannian distance with respect to g .

The shortest geodesic

Proposition

For $p, q \in M$, a curve $\gamma \in \mathcal{C}_{p,q}$ satisfying $d(p, q) = \mathcal{L}(\gamma)$ is a pregeodesic.

Definition

The geodesic $\gamma \in \mathcal{C}_{p,q}$ satisfying $\mathcal{L}(\gamma) = d(p, q)$ is called the minimizing geodesic or the shortest geodesic joining p and q .

Completeness

$\gamma_{p,\mathbf{v}}$: the geodesic with $\gamma_{p,\mathbf{v}}(0) = p$ and $\dot{\gamma}_{p,\mathbf{v}}(0) = \mathbf{v}$.

Definition

- $\gamma_{p,\mathbf{v}}(t)$ is said to be complete if it is defined on \mathbb{R} .
- (M, g) is said to be complete if all geodesics are complete.

Example

The open submanifold $M := \mathbb{E}^n \setminus \{\mathbf{0}\}$ of the Euclidean space \mathbb{E}^n is not complete. In fact, let $\mathbf{x} \in M$ and $\mathbf{v} := -\mathbf{x} \in \mathbb{E}^n = T_{\mathbf{x}}M$. Then the geodesic

$$\gamma_{\mathbf{x},\mathbf{v}}(t) = \mathbf{x} + t\mathbf{v} = (1 - t)\mathbf{x}$$

is defined only on $(-\infty, 1)$.

Hopf-Rinow's Theorem

Theorem (Hopf-Rinow's theorem)

The following are equivalent:

- 1 (M, g) is complete.
- 2 $\exists p \in M$ such that all geodesics emanating at p are complete.
- 3 (M, d) is a complete.
- 4 Any bounded subset D of M is precompact.
- 5 Any divergent path has infinite length.

Example: the Euclidean space

Example

The Euclidean space \mathbb{E}^n is complete. In fact, $\gamma_{\mathbf{x},\mathbf{v}}(t) = \mathbf{x} + t\mathbf{v}$ is defined on \mathbb{R} .

Example: the Shpere

Example

$$S^n := \{ \mathbf{x} \in \mathbb{E}^{n+1}; \langle \mathbf{x}, \mathbf{x} \rangle = 1 \}$$

Then for each $\mathbf{x} \in S^n$ and $\mathbf{v} \in T_{\mathbf{x}}S^n$,

$$\gamma_{\mathbf{x},\mathbf{v}}(t) := (\cos vt)\mathbf{x} + (\sin vt)\mathbf{v}' \quad \left(v = \langle \mathbf{v}, \mathbf{v} \rangle^{1/2}, \quad \mathbf{v}' := \frac{\mathbf{v}}{v} \right).$$

Example: the hyperbolic space

Example

$$H^n := \{ \mathbf{x} = (x^0, \dots, x^{n+1}) \in \mathbb{E}_1^{n+1}; \langle \mathbf{x}, \mathbf{x} \rangle = -1, x^0 > 0 \}.$$

Then for each $\mathbf{x} \in H^n$ and $\mathbf{v} \in T_{\mathbf{x}}H^n$,

$$\gamma_{\mathbf{x}, \mathbf{v}}(t) := (\cosh vt)\mathbf{x} + (\sinh vt)\mathbf{v}' \quad \left(v = \langle \mathbf{v}, \mathbf{v} \rangle^{1/2}, \quad \mathbf{v}' := \frac{\mathbf{v}}{v} \right).$$

Example: de Sitter space

Example

$$S_1^n := \{ \mathbf{x} \in \mathbb{E}_1^{n+1} ; \langle \mathbf{x}, \mathbf{x} \rangle = 1 \} .$$

Then for each $\mathbf{x} \in S_1^n$ and $\mathbf{v} \in T_{\mathbf{x}}S_1^n$,

$$\gamma_{\mathbf{x}, \mathbf{v}}(t) := \begin{cases} (\cos vt)\mathbf{x} + (\sin vt)\mathbf{v}' & \text{if } \langle \mathbf{v}, \mathbf{v} \rangle > 0, \\ \mathbf{x} + t\mathbf{v} & \text{if } \langle \mathbf{v}, \mathbf{v} \rangle = 0, \\ (\cosh vt)\mathbf{x} + (\sinh vt)\mathbf{v}' & \text{if } \langle \mathbf{v}, \mathbf{v} \rangle < 0, \end{cases}$$

where $v := |\langle \mathbf{v}, \mathbf{v} \rangle|^{1/2}$, $\mathbf{v}' := \frac{\mathbf{v}}{v}$.

Ads.

Advanced Topics in Geometry F1 (MTH.B506) @M-143B (H119B)

June 13. 1. Linear Ordinary Differential Equations

June 20. 2. Integrability Condition

June 27. 3. Differential Forms

July 04. 4. Curvature

July 11. 5. Sectional Curvature

July 18. 6. Riemannian manifolds of constant sectional curvature

July 25. 7. Fundamental Theorem for hypersurface theory
