## 1 Inner products

Throughout this section, V denotes an n-dimensional vector space over  $\mathbb{R}$   $(n < \infty)$ .

## **Bilinear forms**

**Definition 1.1.** A symmetric bilinear form on the vector space V is a map  $q: V \times V \to \mathbb{R}$  satisfying the following:

- For each fixed  $\boldsymbol{x} \in V$ , both  $q(\boldsymbol{x}, \cdot) \colon V \ni \boldsymbol{y} \mapsto q(\boldsymbol{x}, \boldsymbol{y}) \in \mathbb{R}$  and  $q(\cdot, \boldsymbol{x}) \colon V \ni \boldsymbol{y} \mapsto q(\boldsymbol{y}, \boldsymbol{x}) \in \mathbb{R}$  are linear maps, and
- $q(\boldsymbol{x}, \boldsymbol{y}) = q(\boldsymbol{y}, \boldsymbol{x})$  holds for  $\boldsymbol{x}, \boldsymbol{y} \in V$ .

A symmetric bilinear form q is said to be *positive definite* if q(x, x) > 0 for any  $x \in V \setminus \{0\}$ .

**Definition 1.2.** An *inner product* on V is a map

 $\langle \ , \ \rangle : V \times V 
i (\boldsymbol{x}, \boldsymbol{y}) \longmapsto \langle \boldsymbol{x}, \boldsymbol{y} \rangle \in \mathbb{R}$ 

which is a positive definite symmetric bilinear form.

**Example 1.3.** We consider  $\mathbb{R}^n$  the vector space consisting of *n*-dimensional *column* vectors. For an  $n \times n$ -symmetric matrix  $A = (a_{ij})$  with real components,

$$q_A \colon \mathbb{R}^n \times \mathbb{R}^n \ni (\boldsymbol{x}, \boldsymbol{y}) \longmapsto \boldsymbol{x}^T A \boldsymbol{y} \in \mathbb{R}.$$

is a symmetric bilinear form, here T denotes the transposition.

Conversely, for each symmetric bilinear form q in  $\mathbb{R}^n$ , there exists a symmetric matrix A such that  $q = q_A$ . In fact, setting  $a_{ij} := q(\mathbf{e}_i, \mathbf{e}_j)$ ,  $A = (a_{ij})$  satisfies  $q = q_A$ , where  $[\mathbf{e}_j]$  is the canonical basis of  $\mathbb{R}^n$ .

**Definition 1.4.** Let  $(V, \langle , \rangle)$  be an *n*-dimensional  $\mathbb{R}$ -vector space with inner product  $\langle , \rangle$ . An *orthonormal basis* of  $(V, \langle , \rangle)$  is an *n*-tuple  $[e_1, \ldots, e_n]$  of elements of V satisfying

$$\langle \boldsymbol{e}_i, \boldsymbol{e}_j \rangle = \delta_{ij} = \begin{cases} 1 & (i=j) \\ 0 & (i \neq j) \end{cases}.$$

**Proposition 1.5.** (1) An orthonormal basis of  $(V, \langle , \rangle)$  is a basis of V.

(2) For two orthonormal bases  $[e_i]$  and  $[f_i]$ , there exists an orthogonal matrix P with

$$\boldsymbol{f}_1,\ldots,\boldsymbol{f}_n]=[\boldsymbol{e}_1,\ldots,\boldsymbol{e}_n]P$$

*Proof.* If  $\mathbf{0} = x^1 \mathbf{e}_1 + \cdots + x^n \mathbf{e}_n$ ,  $x_j = \langle 0, \mathbf{e}_j \rangle = 0$  for  $j = 1, \ldots, n$ . Thus  $[\mathbf{e}_j]$  is linearly independent. So noticing dim V = n, we have (1).

Now we prove (2). If we set  $p_{ij} := \langle \boldsymbol{f}_i, \boldsymbol{e}_j \rangle$  (i, j = 1, ..., n), we have  $\boldsymbol{f}_i = p_{i1}\boldsymbol{e}_1 + \cdots + p_{in}\boldsymbol{e}_n$ , (i = 1, ..., n), in other words  $[\boldsymbol{f}_1, ..., \boldsymbol{f}_n] = [\boldsymbol{e}_1, ..., \boldsymbol{e}_n]P$  holds. Moreover, orthogonality of  $[\boldsymbol{f}_i]$  and  $[\boldsymbol{e}_j]$ , it holds that

$$\delta_{ij} = \langle \boldsymbol{f}_i, \boldsymbol{f}_j \rangle = \sum_{k=1}^n p_{ik} p_{jk} = ij \text{ component of } P^T P.$$

Hence P is an orthogonal matrix.

**Theorem 1.6.** [Existence of an orthonormal basis] For any n-dimensional  $\mathbb{R}$ -vector space  $(V, \langle , \rangle)$ , an orthonormal basis of exists.

Proof. Gram-Schmidt's orthogonalization.

18. April, 2023.

Dual basis The vector space

$$V^* := \{ \alpha \colon V \to \mathbb{R} ; linear \}$$

of linear maps from V to  $\mathbb{R}$  is called the *dual space* of V.

Assume the inner product  $\langle , \rangle$  on V is given, and take an orthonormal basis  $[e_1, \ldots, e_n]$  with respect to  $\langle , \rangle$ . We set then

(1.1) 
$$\omega^j \colon V \ni \boldsymbol{x} \longmapsto \omega^j(\boldsymbol{x}) := \langle \boldsymbol{e}_j, \boldsymbol{x} \rangle \in \mathbb{R}.$$

**Proposition 1.7.** An *n*-tuple  $[\omega^1, \ldots, \omega^n]$  in (1.1) is a basis of  $V^*$ , called the dual basis of  $[e_1, \ldots, e_n]$ .

*Proof.* Assume  $0 = a_1 \omega^1 + \cdots + a_n \omega_n$ , where  $0 \in V^*$  is the zero-map. Substituting  $e_j$  on the both side of it, we have  $a_j = 0$ . Hence  $[\omega^j]$  is linearly-independent. On the other hand, for an arbitrary  $\alpha \in V^*$ , we set  $a_j := \alpha(e_j)$   $(j = 1, \ldots, n)$ . Then  $a_1 \omega^1 + \cdots + a_n \omega^n = \alpha$ , and hence  $V^*$  is spanned by  $[\omega^j]$ .

**Definition 1.8.** For  $\alpha, \beta \in V^*$ , a symmetric bilinear form

$$\alpha\beta \colon V \times V \ni (\boldsymbol{x}, \boldsymbol{y}) \mapsto \frac{1}{2} (\alpha \boldsymbol{x}) \beta(\boldsymbol{y}) + \alpha \boldsymbol{y}) \beta(\boldsymbol{x})$$

is called the symmetric product of  $\alpha$  and  $\beta$ . In particular, when  $\beta = \alpha$ , we denote  $\alpha \alpha$  by  $\alpha^2$  for simplicity.

**Proposition 1.9.** Let  $(V, \langle , \rangle)$  be an n-dimensional vector space V with inner product  $\langle , \rangle$ . Take an orthonormal basis  $[e_i]$  and its dual basis  $[\omega^j]$ . Then

$$\langle , \rangle = (\omega^1)^2 + \dots + (\omega^n)^2.$$

*Proof.* Let  $\boldsymbol{x}, \boldsymbol{y} \in V$ . Then

$$oldsymbol{x} = \sum_{i=1}^n \langle oldsymbol{x}, oldsymbol{e}_i 
angle oldsymbol{e}_i = \sum_{i=1}^n \omega^i(oldsymbol{x}) oldsymbol{e}_i, \qquad ext{and} \qquad oldsymbol{y} = = \sum_{j=1}^n \omega^j(oldsymbol{y}) oldsymbol{e}_j$$

holds. Thus,

$$\langle \boldsymbol{x}, \boldsymbol{y} \rangle = \sum_{i,j=1^n} \omega^i(\boldsymbol{x}) \omega^j(\boldsymbol{y}) \langle \boldsymbol{e}_i, \boldsymbol{e}_j \rangle = \sum_{i=1}^n \omega^i(\boldsymbol{x}) \omega^i(\boldsymbol{y}) = \sum_{i=1}^n (\omega^i)^2(\boldsymbol{x}, \boldsymbol{y}).$$

**The Euclidean vector space** Throughout this lecture, we consider  $\mathbb{R}^n$  as a set of *n*-dimensional *column* vector. We set

$$\langle \boldsymbol{x}, \boldsymbol{y} \rangle := \boldsymbol{x}^T \boldsymbol{y} = \sum_{j=1}^n x^j y^j, \qquad (\boldsymbol{x} = (x^1, \dots, x^n)^T, \boldsymbol{y} = (y^1, \dots, y^n)^T).$$

Then  $\langle , \rangle$  is an inner product, which is called the *canonical inner product*.

**Definition 1.10.** A pair  $\mathbb{E}^n := (\mathbb{R}^n, \langle , \rangle)$  is called the *Euclidean vector space*.

Similarly, we consider  $\mathbb{R}^{n+1}$ , and set

$$\langle \boldsymbol{x}, \boldsymbol{y} \rangle_L := -x^0 y^0 + \sum_{j=1}^n x^j y^j (\boldsymbol{x} = (x^0, x^1, \dots, x^n)^T, \boldsymbol{y} = (y^0, y^1, \dots, y^n)^T),$$

and call it the canonical Lorentz-Minkowski inner product.

**Definition 1.11.** A pair  $\mathbb{L}^{n+1} := (\mathbb{R}^{n+1}, \langle , \rangle_L)$  is called the *Lorentz-Minkowski vector space*.

## Appendix: A Review of Undergraduate Linear Algebra.

- **Definition 1.12.** A square matrix P of real components is said to be an *orthogonal matrix* if  $P^T P = PP^T = I$  holds, where  $P^T$  denotes the transposition of P and I is the identity matrix.
  - A square matrix  $A = (a_{ij})$  is said to be (real) symmetric matrix if  $A^T = A$ , which is equivalent to that  $a_{ij} = a_{ji}$ , holds.
- **Fact 1.13.** The eigenvalues of a real symmetric matrix are real numbers, and the dimension of the corresponding eigenspace coincides with the multiplicity of the eigenvalue.
  - Real symmetric matrices can be diagonalized by orthogonal matrices. In other words, for each real symmetric matrix A, there exists an orthogonal matrix P satisfying

$$P^{-1}AP = P^TAP = \operatorname{diag}(\lambda_1, \dots, \lambda_n),$$

where diag(...) denotes the diagonal matrix with diagonal components "...". In particular,  $\{\lambda_1, \ldots, \lambda_n\}$  are the eigenvalues of A counted with their multiplicity.

## Exercises

**1-1** Let  $\langle , \rangle$  be an inner product of  $\mathbb{R}^2$  defined by

$$\langle oldsymbol{x},oldsymbol{y}
angle := oldsymbol{x}^T A oldsymbol{y} \qquad A = egin{pmatrix} 1 & a \ a & 1 \end{pmatrix},$$

where a is a real number with |a| < 1.

- Find an orthonormal basis  $[e_1, e_2]$  with respect to  $\langle , \rangle$ .
- Find row vectors  $\hat{\omega}^{j}$  (j = 1, 2) such that the dual basis  $[\omega^{j}]$  of  $[e_{j}]$  is expressed as

$$\omega^j(\boldsymbol{x}) = \hat{\omega}^j \boldsymbol{x} \qquad (j = 1, 2).$$

1-2 Let  $\mathbb{L}^3$  be the 3-dimensional Lorentz-Minkowski vector space, and fix  $x \in \mathbb{L}^3$  with  $\langle x, x \rangle_L = -1$ . Take the "orthogonal complement"

$$W:=oldsymbol{x}^{\perp}=\{oldsymbol{y}\in\mathbb{L}^3\,;\,\langleoldsymbol{x},oldsymbol{y}
angle\}.$$

- Show that W is an 2-dimensional linear subspace of  $\mathbb{L}^3$ .
- Show that the restriction of  $\langle \;,\;\rangle_L$  to  $W\times W$  is a (positive definite) inner product of W.