5 Riemannian connection

Riemannian connection Let (M, g) be a (pseudo) Riemannian manifold, and denote by \langle , \rangle the inner product induced by g. We let $\mathcal{F}(M)$ and $\mathfrak{X}(M)$ be the set of smooth functions and smooth vector fields on M, respectively.

Lemma 5.1. There exists the unique bilinear map

$$\nabla \colon \mathfrak{X}(M) \times \mathfrak{X}(M) \ni (X, Y) \longmapsto \nabla_X Y \in \mathfrak{X}(M)$$

satisfying

- $\nabla_X Y \nabla_Y X = [X, Y],$
- $X \langle Y, Z \rangle = \langle \nabla_X Y, Z \rangle + \langle Y, \nabla_X Z \rangle$

for X, Y, $Z \in \mathfrak{X}(M)$, where [,] denotes the Lie bracket in Definition 4.1.

Proof. Set

(5.1)
$$C(X,Y,Z) := \frac{1}{2} \left(X \left\langle Y,Z \right\rangle + Y \left\langle Z,X \right\rangle - Z \left\langle X,Y \right\rangle - \left\langle Y,[X,Z] \right\rangle + \left\langle X,[Z,Y] \right\rangle - \left\langle Z,[Y,X] \right\rangle \right).$$

Then there exists unique vector field $\nabla_X Y$ satisfying

$$\langle \nabla_X Y, Z \rangle = C(X, Y, Z).$$

This is the desired one.

Definition 5.2. The map ∇ in Lemma 5.1 is called the *Riemannian connection* or the *Levi-Civita connection*.

Lemma 5.3. The Levi-Civita connection satisfies

- $\nabla_{fX}Y = f\nabla_XY$,
- $\nabla_X(fY) = f\nabla_X Y + (Xf)Y$

for all $X, Y \in \mathfrak{X}(M)$ and $f \in \mathcal{F}(M)$.

Proof. Lemma 4.2 and the equation (5.1) yields the conclusion.

Corollary 5.4. Assume $X, Y \in \mathfrak{X}(M)$ satisfy $X_p = Y_p$ at a point $p \in M$. Then

$$(\nabla_X Z)_p = (\nabla_Y Z)_p$$

holds for each $Z \in \mathfrak{X}(M)$.

Proof. Take an $n = \dim M$ -tuple of vector fields $[e_1, \ldots, e_n]$ on a domain $U \subset M$ which gives a basis of T_pM for each point $p \in U$. Then a vector field X is expressed as

$$X = \sum_{j=1}^{n} X^{j} \boldsymbol{e}_{j}$$
 and $Y = \sum_{j=1}^{n} Y^{j} \boldsymbol{e}_{j}$

where X^j and Y^j are smooth functions satisfying $X^j(p) = Y^j(p)$ (j = 1, ..., n). Then by the first assertion of Lemma 5.3, we have

$$(\nabla_X Z)_p = \sum_{j=1}^n X^j(p) (\nabla_{\boldsymbol{e}_j} Z)_p = \sum_{j=1}^n Y^j(p) (\nabla_{\boldsymbol{e}_j} Z)_p = (\nabla_Y Z)_p.$$

Definition 5.5. For $x \in T_pM$ be a tangent vector at $p \in M$ and a vector field $Y \in \mathfrak{X}(M)$,

$$\nabla_{\boldsymbol{x}} Y := (\nabla_X Y)_p \in T_p M$$

is called the *covariant derivative* of Y with respect to the direction \boldsymbol{x} , where $X \in \mathfrak{X}(M)$ is a vector field satisfying $X_p = \boldsymbol{x}$.

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Examples

Example 5.6. Let \mathbb{E}_r^{n+r} be the pseudo Euclidean space and \langle , \rangle the inner product of signature (n, r). Then the the canonical connection (cf. (4.4)) D defined by

$$D: \mathfrak{X}(\mathbb{E}_r^{n+r}) \times \mathfrak{X}(\mathbb{E}_r^{n+r}) \ni (X,Y) \longmapsto D_X Y := dY(X) \in \mathfrak{X}(M)$$

c is the Levi-Civita connection, because of Lemma 4.6.

Lemma 5.7. Let $M \subset \mathbb{E}_r^{n+r}$ be a submanifold of the pseudo Euclidean space \mathbb{E}_r^{n+r} . If the restriction of the inner product \langle , \rangle of \mathbb{E}_r^{n+r} on T_pM is non-degenerate, the direct sum decomposition

$$\mathbb{E}_r^{n+r} = T_p M \oplus (T_p M)^{\perp}, \qquad (T_p M)^{\perp} := \{ \boldsymbol{v} \in \mathbb{E}_r^{n+r} ; \langle \boldsymbol{x}, \boldsymbol{v} \rangle = 0 \text{ for all } \boldsymbol{x} \in T_p M \},$$

that is, for each vector $\mathbf{v} \in \mathbb{E}_r^{n+r} = T_p \mathbb{E}_r^{n+r}$, there exists a unique decomposition

(5.2)
$$\boldsymbol{v} = [\boldsymbol{v}]^{\mathrm{T}} + [\boldsymbol{v}]^{\mathrm{N}}, \qquad [\boldsymbol{v}]^{\mathrm{T}} \in T_p M, \qquad [\boldsymbol{v}]^{\mathrm{N}} \in (T_p M)^{\perp}.$$

The vectors $[\boldsymbol{v}]^{\mathrm{T}}$ and $[\boldsymbol{v}]^{\mathrm{N}}$ in (5.2) are called the *tangential component* and *normal component* of \boldsymbol{v} , respectively.

Proof. By the relationship of rank and kernel, $\dim T_pM + \dim(T_pM)^{\perp} = \dim \mathbb{E}_r^{n+r}$. Let $\boldsymbol{v} \in T_pM \cap (T_pM)^{\perp}$. Since \boldsymbol{v} in $(T_pM)^{\perp}$, $\langle \boldsymbol{v}, \boldsymbol{w} \rangle = 0$ for all $\boldsymbol{w} \in T_pM$. Here $\boldsymbol{v} \in T_pM$ and $\langle , \rangle |_{T_pM}$ is non-degenerate, $\boldsymbol{v} = \boldsymbol{0}$. Hence the conclusion follows.

Remark 5.8. When r = 0, that is, the case that \mathbb{E}^n is the Euclidean space, the non-degeneracy assumption of Lemma 5.7 is empty. On the other hand, in \mathbb{E}^3_1 , for example,

$$M := \{(u, u, v); u, v \in \mathbb{R}\}$$

does not satisfy the non-degeneracy assumption. In fact, $T_pM = \text{Span}\{\boldsymbol{v}_1, \boldsymbol{v}_2\}$, where $\boldsymbol{v}_1 = (1, 1, 0)^T$ and $\boldsymbol{v}_2 = (0, 0, 1)^T$. Then $\langle \boldsymbol{v}_1, \boldsymbol{x} \rangle = 0$ for all $\boldsymbol{x} \in T_pM$, that is, $\langle , \rangle |_{T_pM}$ degenerates. In this case, $(T_pM)^{\perp} = \mathbb{R}\boldsymbol{v}_1 \subset T_pM$.

Theorem 5.9. Let $M \subset \mathbb{E}_r^{n+r}$ be a submanifold such that the restriction of the inner product \langle , \rangle to TM is non-degenerate. We set $\nabla_X Y$ for $X, Y \in \mathfrak{X}(M)$ by

$$\nabla_X Y := \left[D_X Y \right]^{\mathrm{T}}.$$

Then ∇ is the Levi-Civita connection of M with respect to the induced metric $\langle , \rangle |_{TM}$.

Proof. For X and $Y \in \mathfrak{X}(M)$, $[X, Y] \in \mathfrak{X}(M)$ holds. Hence

$$\nabla_X Y - \nabla_Y X = [D_X Y - D_Y X]^{\mathrm{T}} = [[X, Y]]^{\mathrm{T}} = [X, Y]$$

yield the first assertion of Lemma 5.1. On the other hand,

$$X \langle Y, Z \rangle = \langle D_X Y, Z \rangle + \langle Y, D_X Z \rangle = \left\langle \left[D_X Y \right]^{\mathrm{T}}, Z \right\rangle + \left\langle Y, \left[D_X Z \right]^{\mathrm{T}} \right\rangle = \left\langle \nabla_X Y, Z \right\rangle + \left\langle Y, \nabla_X Z \right\rangle.$$

Hence ∇ is the Levi-Civita connection.

Exercises

 Set

$$H^{2}(-1) = \{ \boldsymbol{x} = (x^{0}, x^{1}, x^{2})^{T} \in \mathbb{E}_{1}^{3}; \, \langle \boldsymbol{x}, \boldsymbol{x} \rangle = -1, x^{0} > 0 \},\$$

and take a parametrization

$$f: D \ni (u, v) \mapsto \frac{1}{1 - u^2 - v^2} (1 + u^2 + v^2, 2u, 2v) \in H^2(-1)$$

of $H^2(-1)$, where $D := \{(u, v) \in \mathbb{R}^2 ; u^2 + v^2 < 1\}.$

5-1 Let $[e_0(u, v), e_1(u, v), e_2(u, v)]$ be an orthonormal frame defined by

$$oldsymbol{e}_0 := oldsymbol{f}, \qquad oldsymbol{e}_1 := rac{oldsymbol{f}_u}{|oldsymbol{f}_u|}, \qquad oldsymbol{e}_2 := rac{oldsymbol{f}_v}{|oldsymbol{f}_v|}$$

as in Problem 4-1. For the induced connection ∇ of $H^2(-1)$,

- Compute $\langle \nabla \boldsymbol{e}_i \boldsymbol{e}_j, \boldsymbol{e}_k \rangle$ for i, j and k run over $\{1, 2\}$.
- Compute

$$\nabla \boldsymbol{e}_1 \nabla \boldsymbol{e}_2 \boldsymbol{e}_2 - \nabla \boldsymbol{e}_2 \nabla \boldsymbol{e}_1 \boldsymbol{e}_2 - \nabla [\boldsymbol{e}_1, \boldsymbol{e}_2] \boldsymbol{e}_2.$$

5-2 Let $\widetilde{D} := (0, \infty) \times (-\pi, \pi)$ and take another parametrization

 $\widetilde{\boldsymbol{f}}:\widetilde{D}\ni(r,t)\mapsto(\cosh r,\sinh r\cos t,\sinh r\sin t)^T\in H^2(-1)$

of $H^2(-1)$, and set

$$\boldsymbol{v}_0 = \widetilde{\boldsymbol{f}}, \qquad \boldsymbol{v}_1 = \widetilde{\boldsymbol{f}}_r, \qquad \boldsymbol{v}_2 = \frac{1}{\sinh r} \widetilde{\boldsymbol{f}}_t.$$

- Find a parameter change $\varphi \colon (r,t) \mapsto (u,v) = (u(r,t),v(r,t)).$
- Find a 2 \times 2-matrix valued function $\Theta=\Theta(r,t)$ satisfying

$$[\boldsymbol{e}_1, \boldsymbol{e}_2] = [\boldsymbol{v}_1, \boldsymbol{v}_2]\boldsymbol{\Theta},$$

where the left-hand side and the right-hand side are valuated at (u(r,t), v(r,t)) and (r,t), respectively.