

Advanced Topics in Geometry B1 (MTH.B406)

Hyperbolic Space

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Hyperbolic plane

work on general dimensions

$$(x_0 - x_1) = x_0^2 - x_1^2 = 1 + x_2^2 > 0$$

$$\checkmark x_0 + x_1 > 0$$

$$H^2 := \{x = (x_0, x_1, x_2)^T \in \mathbb{L}^3; \langle x, x \rangle = -1, x_0 > 0\}$$

$$\rightarrow (1, 0, 0)$$

$$\mathbb{R}_+^2 := \{(x, y) \in \mathbb{R}^2; y > 0\}, \quad ds^2 = \frac{dx^2 + dy^2}{y^2}$$

$$\pi: H^2 \ni (x_0, x_1, x_2) \mapsto \left(\frac{x_2}{x_0 + x_1}, \frac{1}{x_0 + x_1} \right) \in \mathbb{R}_+^2.$$

$$\boxed{y > 0}$$

► π is an isometry

(diffeo)

$\exists$ inverse

$$x_2 = \frac{x}{y}$$

$$x_0 + x_1 = \frac{1}{y}$$

$$x_0 - x_1 = \frac{1 + x_2^2}{x_0 + x_1} = \frac{1 + \frac{x^2}{y^2}}{\frac{1}{y}} = \frac{y^2 + x^2}{y}$$

$$x_0 = \frac{1+x^2+y^2}{2y}, \quad x_1 = \frac{1-x^2-y^2}{2y}, \quad x_2 = \frac{x}{y}$$

$$\underline{\underline{-dx_0^2 + dx_1^2 + dx_2^2}}$$

Lorentzian

$$= \frac{dx^2 + dy^2}{y^2} = \underline{\underline{ds^2}}$$

$$H^2 \underset{P}{=} (\mathbb{R}_+^2, ds^2)$$

as a Riem manifold

Straight lines

Lemma

Let

$$\sigma(t) = \sigma_{c,r}(t) := \begin{cases} (r \tanh t + c, r \operatorname{sech} t) & (0 < r < \infty), \\ (c, e^t) & (r = +\infty), \end{cases}$$

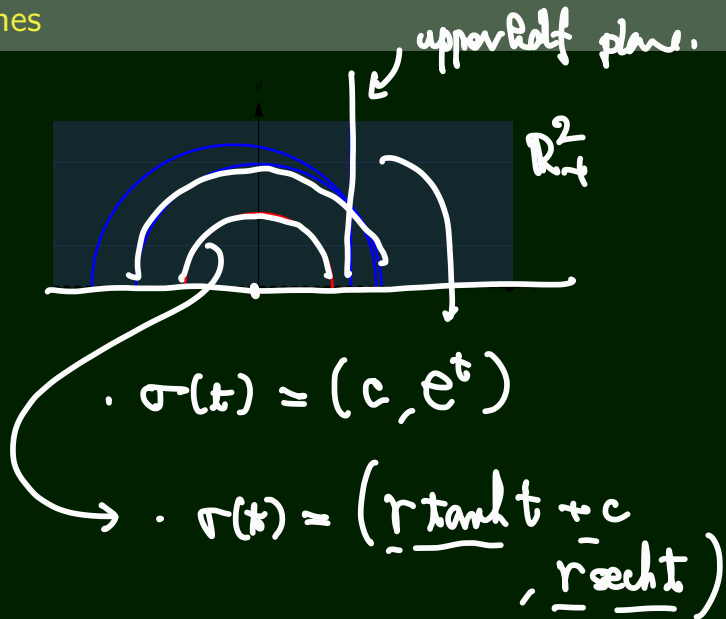
where $c \in \mathbb{R}$. Then

$$\pi^{-1} \circ \sigma(t) = (\cosh t)x + (\sinh t)v$$

for some $x \in H^2$ and $v \in T_x H^2$ with $\langle v, v \rangle = 1$.

"great circle" on H^2 in $H^2 \subset \mathbb{L}^3$

Straight lines



Straight lines

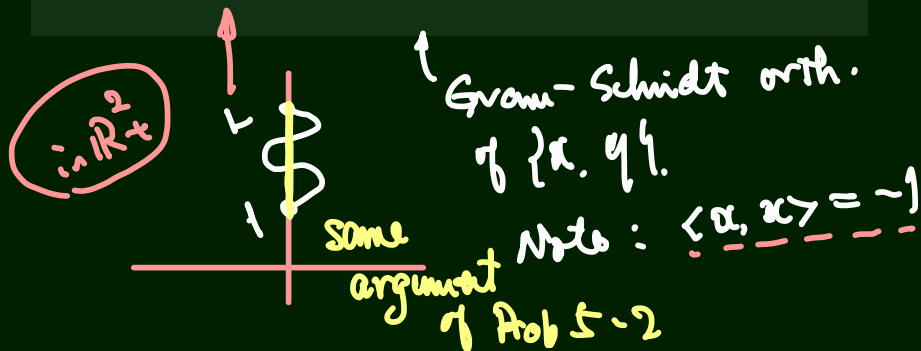
- ▶ $T_x H^2 = x^\perp$
- ▶ $U_x H^2 = \{v \in T_x H^2; \langle v, v \rangle = 1\}$.
- $\gamma_{x,v}(t) := \underline{(\cosh t)x + (\sinh t)v}$. •  ← "shortest path"
- ▶ γ is a curve in H^2 with $\gamma(0) = x$, $\gamma'(0) = v$. •
- ▶ $\langle \gamma', \gamma' \rangle = 1$, i.e., t is the arc-length parameter.

Straight line

Proposition

The shortest path joining two distinct points x and $y \in H^2$ is parametrized as $\gamma_{x,v}$, where

$$v = \frac{y + \langle x, y \rangle x}{|y + \langle x, y \rangle x|} \in U_x H^2$$

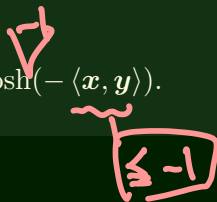


Distance

Proposition

For $x, y \in H^2$,

- $\text{dist}(x, y) = \cosh(-\langle x, y \rangle).$



Pythagorean theorem

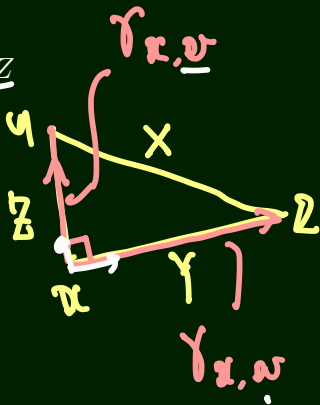
$$\cosh X = \cosh Y \cosh Z$$

$$v = \frac{y + \langle \alpha, y \rangle \alpha}{1 + \langle \alpha, y \rangle}$$

$$w = \frac{z + \langle \alpha, z \rangle \alpha}{1 + \langle \alpha, z \rangle}$$

$$v \perp w$$

$$0 = \langle v, w \rangle \Rightarrow \frac{-\langle y, z \rangle}{1 + \langle \alpha, y \rangle (1 + \langle \alpha, z \rangle)}$$

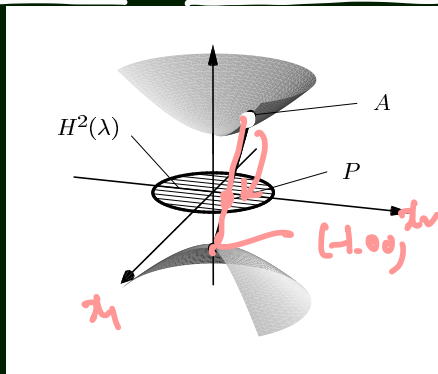


Poincaré disc model

Stereographic projection:

(cf. $S^2 \setminus \{1 \text{ point}\} \rightarrow \mathbb{C}$)

- $D := \{(u, v) ; u^2 + v^2 < 1\}$.
- $\pi_P : H^2 \ni (x_0, x_1, x_2) \mapsto (u, v) = \frac{1}{1+x_0}(x_1, x_2) \in D$.

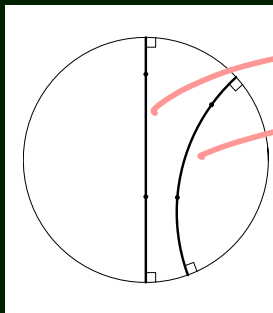


Poincaré disc model

Poincaré disc model:

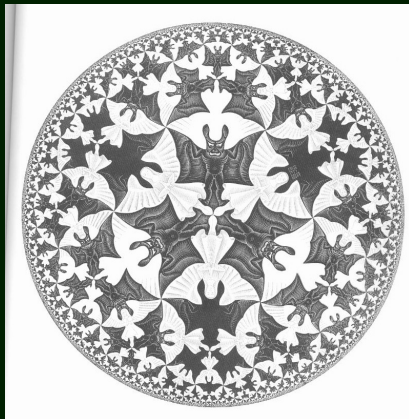
$$D = \{(u, v) ; u^2 + v^2 < 1\},$$

$$ds^2 = \frac{4}{(1 - u^2 - v^2)^2} (du^2 + dv^2).$$



lines

Poincaré disc model



Circle limit IV (M.C. Escher, 1960)

Klein model

Central projection:

► $D := \{(\xi, \eta) ; \xi^2 + \eta^2 < 1\}.$

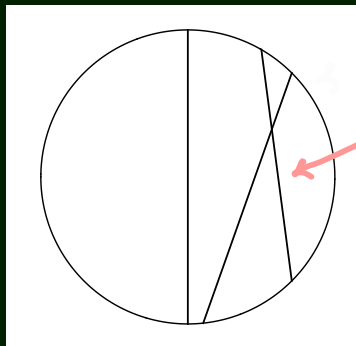
► $\pi_C: H^2 \ni (x_0, x_1, x_2) \mapsto (\xi, \eta) = \frac{1}{x_0}(x_1, x_2) \in D.$

$$ds_C^2 = \frac{1}{(1 - \xi^2 - \eta^2)} ((1 - \eta^2) d\xi^2 + 2\xi\eta d\xi d\eta + (1 - \xi^2) d\eta^2).$$

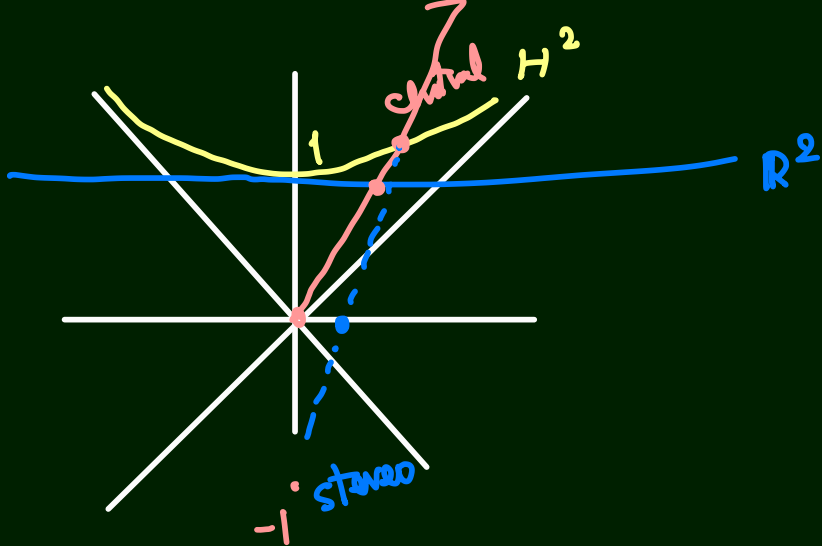
"projective model"

19c.

Beltrami



straight
lines



Final Remarks

- ▶ Non-Euclidean geometry

• Virtual object.

- ▶ Pseudospherical surfaces

Locally realizable

B. Bonfanti

not complete

- ▶ Construction of Pseudospherical surfaces

Integrable systems.

$\Rightarrow$ many local models

- ▶ Non-existence of models of non-Euclidean geometry as surfaces in $\mathbb{R}^3$ (Hilbert)

$\nexists$ global models.

- ▶ A model of non-Euclidean geometry as a surface in Lorentz-Minkowski space.

hyperboloid

- ▶ Various models of non-Euclidean geometry.

Enjoy!